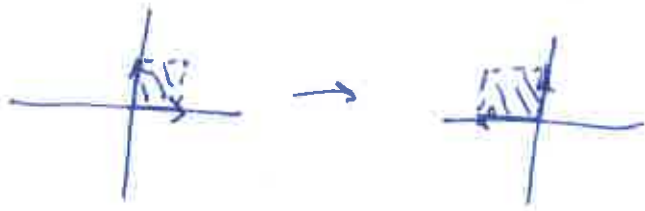


Matrix monsters

$A \in M_{t \times s}(\mathbb{R})$ gives $T_A: \mathbb{R}^s \rightarrow \mathbb{R}^t$
 $v \mapsto Av$

Example 5 $A = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ gives $T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} -x \\ y \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$
 $\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} -1 \\ 0 \end{pmatrix}$
 $\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 0 \\ 1 \end{pmatrix}$



T_A is reflection in the y -axis

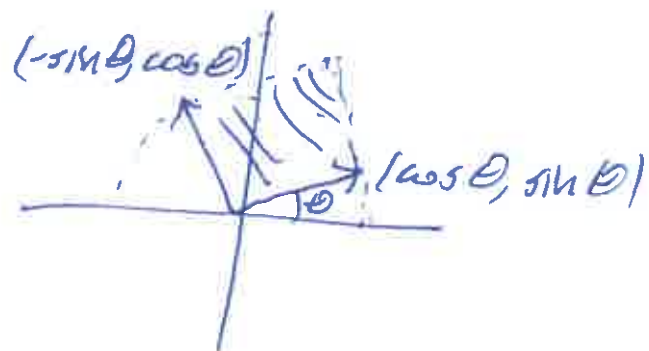
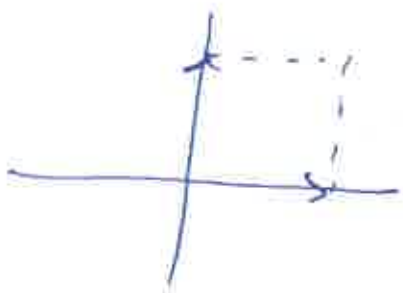
Example 7 $A = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ gives

$$T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$$

T_A is rotation in the angle θ .

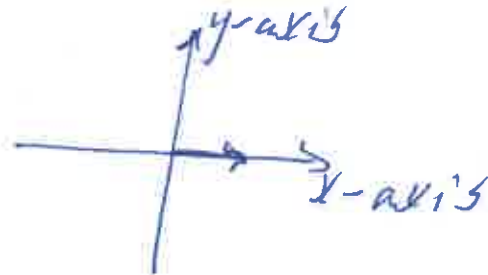
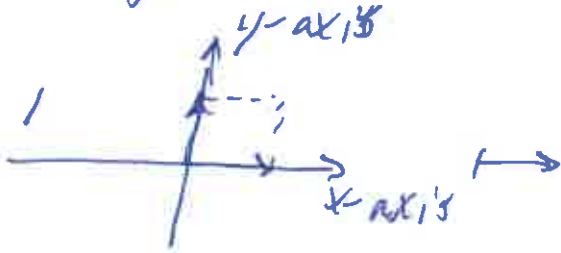


Example 19

$A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ gives

$T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x \\ 0 \end{pmatrix}$

T_A is projection onto the x -axis



$\ker(T_A) = \left\{ \begin{pmatrix} 0 \\ y \end{pmatrix} \mid y \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$

$\text{Im}(T_A) = \left\{ \begin{pmatrix} x \\ 0 \end{pmatrix} \mid x \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$

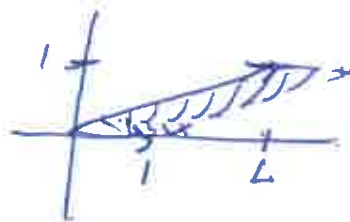
Example 8 $A = \begin{pmatrix} c & 0 \\ 0 & 1 \end{pmatrix}$ gives $T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$



$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} c \\ 0 \end{pmatrix}$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

Example 9 $A = \begin{pmatrix} 1 & c \\ 0 & 1 \end{pmatrix}$ gives $T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$



$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} c \\ 1 \end{pmatrix}$

T_A is shear along the x -axis with $c=1$.

$$[T]_{CC} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

The transition matrix from $B = \{ |1, 0\rangle, |0, 1\rangle \}$ to C is

$$P_{CB} = \begin{pmatrix} 1 & 5 \\ 5 & -1 \end{pmatrix} \text{ since } \begin{aligned} |1, 0\rangle &= 1 \cdot |1, 0\rangle + 5 |0, 1\rangle \\ |5, -1\rangle &= 5 \cdot |1, 0\rangle + (-1) |0, 1\rangle. \end{aligned}$$

The inverse of P_{CB} is

$$P_{CB}^{-1} = \begin{pmatrix} -1 & -5 \\ -5 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 26 \end{pmatrix} = \begin{pmatrix} \frac{1}{26} & \frac{+5}{26} \\ \frac{+5}{26} & \frac{-1}{26} \end{pmatrix} = P_{BC}$$

The matrix of T with respect to the basis B is

$$[T]_{BB} = P_{BC} [T]_{CC} P_{CB}$$

$$= \begin{pmatrix} \frac{1}{26} & \frac{5}{26} \\ \frac{5}{26} & \frac{-1}{26} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 5 \\ 5 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{26} & \frac{5}{26} \\ \frac{5}{26} & \frac{-1}{26} \end{pmatrix} \begin{pmatrix} 1 & 5 \\ -5 & 1 \end{pmatrix} = \begin{pmatrix} \frac{-24}{26} & \frac{10}{26} \\ \frac{10}{26} & \frac{24}{26} \end{pmatrix}$$

$$= \begin{pmatrix} \frac{-12}{13} & \frac{5}{13} \\ \frac{5}{13} & \frac{12}{13} \end{pmatrix}$$