

Jordan Normal Form

Let  $A$  be an  $n \times n$  matrix.

If  $I = \{i_1, \dots, i_m\}$  is a subset of  $\{1, 2, \dots, n\}$  and  $J = \{j_1, \dots, j_m\}$  another subset of  $\{1, 2, \dots, n\}$

the  $(I, J)$  minor of  $t - A$  is

$$\det(t - A)_{IJ} = \det \begin{pmatrix} (t - A)_{i_1 j_1} & (t - A)_{i_1 j_2} & \cdots & (t - A)_{i_1 j_m} \\ \vdots & \ddots & & \vdots \\ (t - A)_{i_m j_1} & (t - A)_{i_m j_2} & \cdots & (t - A)_{i_m j_m} \end{pmatrix}$$

If  $I$  and  $J$  have  $m$  elements  $\det(t - A)_{IJ}$  is an  $m^{\text{th}}$  order minor of  $t - A$ .

The gcd of the  $m^{\text{th}}$  order minors of  $t - A$  is

$$d_m(t) = \gcd \left\{ \det(t - A)_{IJ} \mid \begin{array}{l} \text{det}(t - A)_{IJ} \text{ is an } m^{\text{th}} \text{ order} \\ \text{minor of } t - A \end{array} \right\}$$

The similarity invariants of  $A$ , or invariant factors of  $t - A$ , are monic polynomials  $q_1(t), \dots, q_n(t)$  such that

$$d_m(t) = q_1(t) q_2(t) \cdots q_m(t), \quad \text{for } m=1, 2, \dots, n$$

$$(\text{i.e. } q_m(t) = \frac{d_m(t)}{d_{m-1}(t)}).$$

The characteristic polynomial of  $A$  is  $d_n(t)$ .

Theorem The minimal polynomial of  $A$  is  $q_n(t)$ .

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A Jordan block of type  $(t-\lambda)^e$  is the

ex matrix

$$\begin{pmatrix} \lambda & & & \\ 1 & \lambda & & 0 \\ & 1 & \lambda & \dots \\ & & \ddots & \\ 0 & & & \lambda \end{pmatrix}$$

Factor the  $q_1(t), q_2(t), \dots, q_n(t)$ :

$$q_1(t) = (t - \lambda_1)^{e_{11}} (t - \lambda_2)^{e_{12}} \dots (t - \lambda_k)^{e_{1k}}$$

$$q_2(t) = (t - \lambda_1)^{e_{21}} (t - \lambda_2)^{e_{22}} \dots (t - \lambda_k)^{e_{2k}}$$

$$\vdots$$

$$q_n(t) = (t - \lambda_1)^{e_{n1}} (t - \lambda_2)^{e_{n2}} \dots (t - \lambda_k)^{e_{nk}}$$

Theorem There exists an invertible matrix  $P$  such that

$$PAP^{-1} = \begin{pmatrix} J_{11} & & & & \\ & J_{12} & & & \\ & & \ddots & & \\ & & & J_{1k} & \\ & & & & J_{21} \\ & & & & & \ddots \\ & & & & & & 0 \\ & & & & & & & \ddots \\ & & & & & & & & 0 \\ & & & & & & & & & \ddots \\ & & & & & & & & & & J_{n,k-1} \\ & & & & & & & & & & & J_{n,k} \end{pmatrix}$$

where  $J_{me}$  is a Jordan block of type  $(t - \lambda_e)^{e_{me}}$

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Example If  $A = \begin{pmatrix} 2 & 1 & 3 \\ 5 & 0 & 1 \\ 2 & 6 & 3 \end{pmatrix}$  then  $t-A = \begin{pmatrix} t-2 & 1 & 3 \\ 5 & t & 1 \\ 2 & 6 & t-3 \end{pmatrix}$

Subsets of  $\{1, 2, 3\}$

If  $I$  and  $J$  have 3 elements then  $I = \{1, 2, 3\} = J$  and  $(t-A)_{IJ} = t-A$  and  $d_3 = \det(t-A)$ . So

$$\begin{aligned} d_3(t) &= \det(t-A) = (t-2)(t^2-3t-6) - (5t-15-2) + 3(30-2t) \\ &= t^3 - 3t^2 - 4t - 2t^2 + 6t + 12 - 5t + 17 + 90 - 6t \\ &= t^3 - 5t^2 - 11t + 119 \end{aligned}$$

If  $I$  and  $J$  have 1 element then  $(t-A)_{IJ}$  is a single entry of  $t-A$ . So

$$d_1(t) = \gcd\{t-2, 1, 3, 5, t, 1, 2, 6, t-3\} = 1.$$

If  $I$  and  $J$  have 2 elements then

$I$  is  $\{1, 2\}$  or  $\{1, 3\}$  or  $\{2, 3\}$  and

$J$  is  $\{1, 2\}$  or  $\{1, 3\}$  or  $\{2, 3\}$  and

$$\begin{aligned} d_2(t) &= \gcd \left\{ \det \begin{pmatrix} t-2 & 1 \\ 5 & t \end{pmatrix}, \det \begin{pmatrix} t-2 & 3 \\ 5 & 1 \end{pmatrix}, \det \begin{pmatrix} 1 & 3 \\ t & 1 \end{pmatrix}, \right. \\ &\quad \left. \det \begin{pmatrix} t-2 & 1 \\ 2 & 6 \end{pmatrix}, \det \begin{pmatrix} t-2 & 3 \\ 2 & t-3 \end{pmatrix}, \det \begin{pmatrix} 1 & 3 \\ 6 & t-3 \end{pmatrix}, \right. \\ &\quad \left. \det \begin{pmatrix} 5 & t \\ 2 & 6 \end{pmatrix}, \det \begin{pmatrix} 5 & 1 \\ 2 & t-3 \end{pmatrix}, \det \begin{pmatrix} t & 1 \\ 6 & t-3 \end{pmatrix} \right\} \end{aligned}$$

$$= \gcd\{t^2-2t-5, t-10, 1-3t, \dots, 5t-17, t^2-3t-6\} = 1.$$

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Wolfram alpha tells us that

$$t^3 - 5t^2 - 11t + 119$$

$$= (t + 4.23445)(t - (4.61723 + 2.60462i))(t - (4.61723 - 2.60462i))$$

$$(t - (4.61723 - 2.60462i))$$

Since  $d_1(t) = q_1(t)$ ,  $d_2(t) = q_1(t)q_2(t)$ ,  $d_3(t) = q_1(t)q_2(t)q_3(t)$  and

$$d_1(t) = 1$$

$$q_1(t) = 1$$

$$d_2(t) = 1$$

$$q_2(t) = 1$$

$$d_3(t) = t^3 - 5t^2 - 11t + 119,$$

$$q_3(t) = t^3 - 5t^2 - 11t + 119$$

then

and the factorization of  $q_1(t)$ ,  $q_2(t)$  and  $q_3(t)$  are

$$q_1(t) = (t - \alpha_1)^0(t - \alpha_2)^0(t - \alpha_3)^0$$

$$q_2(t) = (t - \alpha_1)^0(t - \alpha_2)^0(t - \alpha_3)^0$$

$$q_3(t) = (t - \alpha_1)^1(t - \alpha_2)^1(t - \alpha_3)^1$$

where

$$\alpha_1 = 4.23445, \quad \alpha_2 = 4.61723 + i2.60462,$$

$$\alpha_3 = 4.61723 - i2.60462.$$

The Jordan normal form theorem then says that there exists  $P$  such that

$$PAP^{-1} = P \begin{pmatrix} 2 & 1 & 3 \\ 5 & 0 & 1 \\ 2 & 6 & 3 \end{pmatrix} P^{-1} = \begin{pmatrix} \alpha_1 & 0 & 0 \\ 0 & \alpha_2 & 0 \\ 0 & 0 & \alpha_3 \end{pmatrix}$$

with  $\alpha_1, \alpha_2, \alpha_3$  as above.